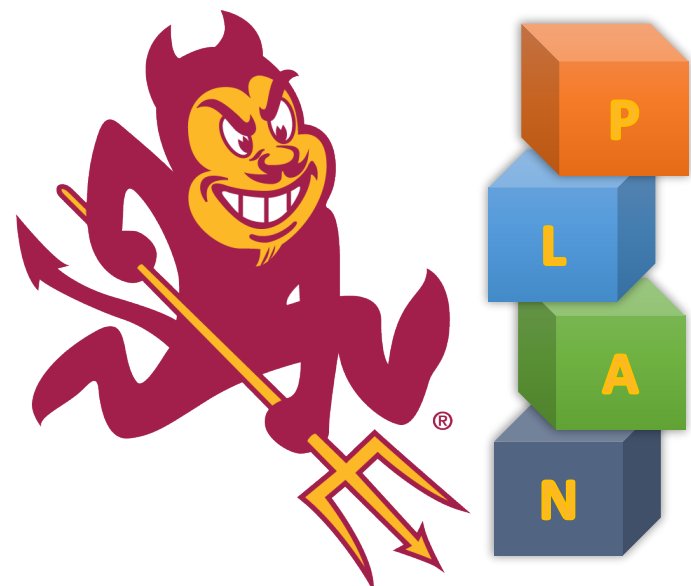


CAP - A Decision Support System for Crew Scheduling using Automated Planning



Aditya Prasad Mishra, **Sailik Sengupta***, Sarath Sreedharan, Tathagata Chakraborti and Subbarao Kambhampati

Problem

- A team of crew members are expected to perform a set of tasks (or achieve some goals) when on a mission.
- A human planner, who has a holistic view of the system can make a schedule for the crew.
- There may exist organizational and temporal ordering constraints which have to be accounted for when coming up with this schedule.

In this work, we come up with a schedule authoring system that aids the human planner to come up with a schedule that fulfills all the requirements.

Representation

- We model the scheduling problem as an automated planning problem and represent it using the Planning Domain Definition Language (PDDL).

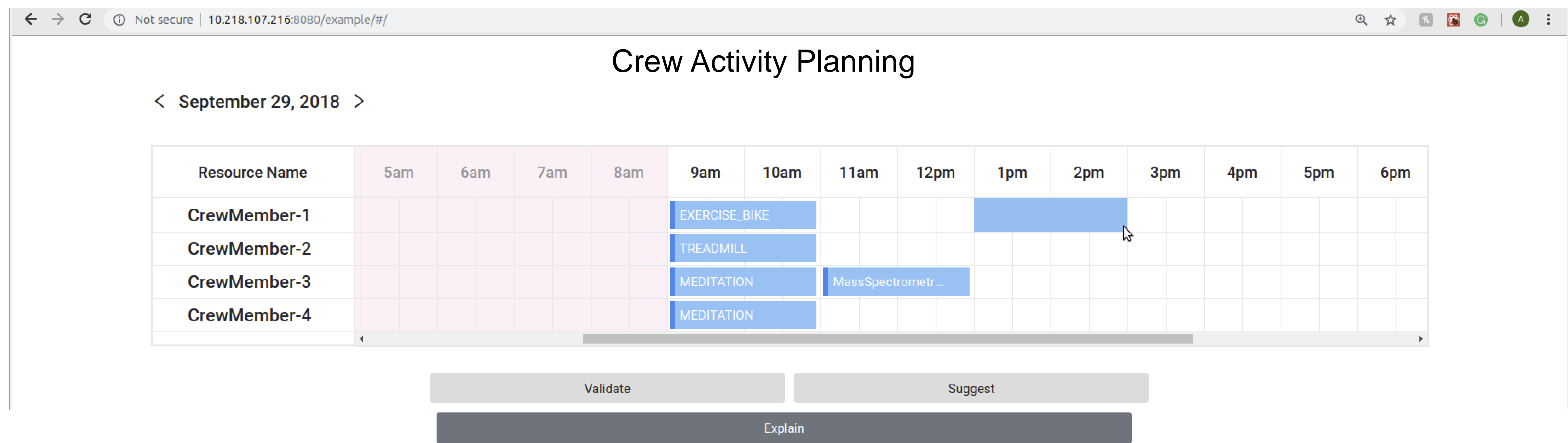
```

...
(:action close_door
:precondition (and
(photo_taken)
(camera_equipment_removed)
) :effect (and
(door_closed)
(not (latch_open))
))
...
<F, A, I, G>
...
(:init
(=(number_of_crew_members)4)
(not(complete_day))
...
)
(:goal (and
(CubeRRT_finished)
...
(complete_day)
))
    
```

Scheduling Domain

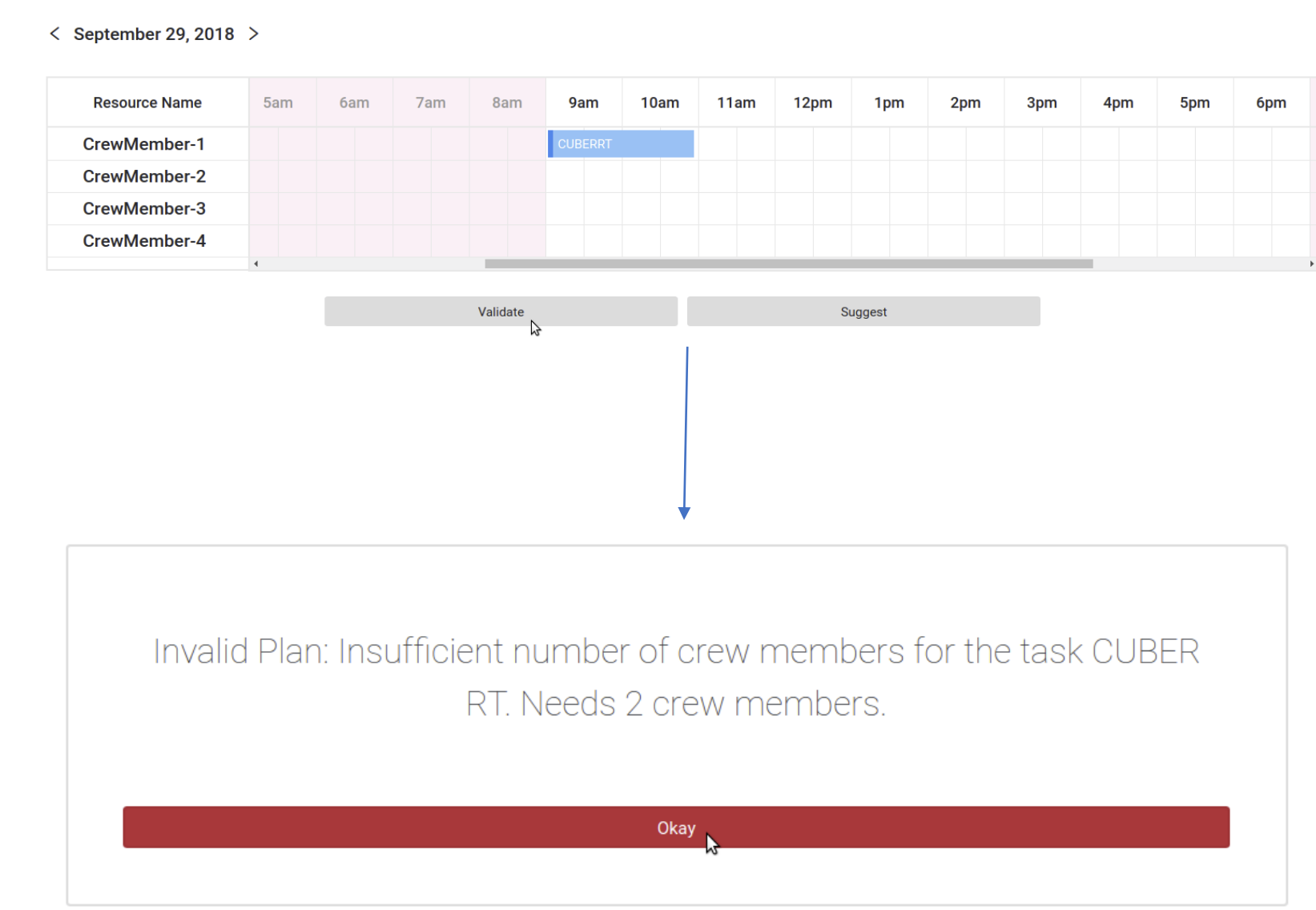
- Previous work by NASA creates a plan authoring tool to aid human planners (focuses on UI design, does not use artificial intelligence in the backend to provide decision support).
- We create a mock scenario that makes a **ten** hour plan with **four** crew members in this domain to achieve a goal in which,

- Some science experiments have to be completed:** CubeRRt, Advanced_Diagnostic_Ultrasound_in_Microgravity
- Some crew members need to exercise on a treadmill.**
- Communication** has to be done when the space craft is in line of sight with the ground station.
- Photos** have to be taken for certain parts of the planet.
- Repair Tasks** have to be performed on certain parts of the aircraft.



Plan Validation

- Plans being constructed can be validated using VAL at any point in time. VAL highlights the reason when it finds a plan being constructed is not valid.



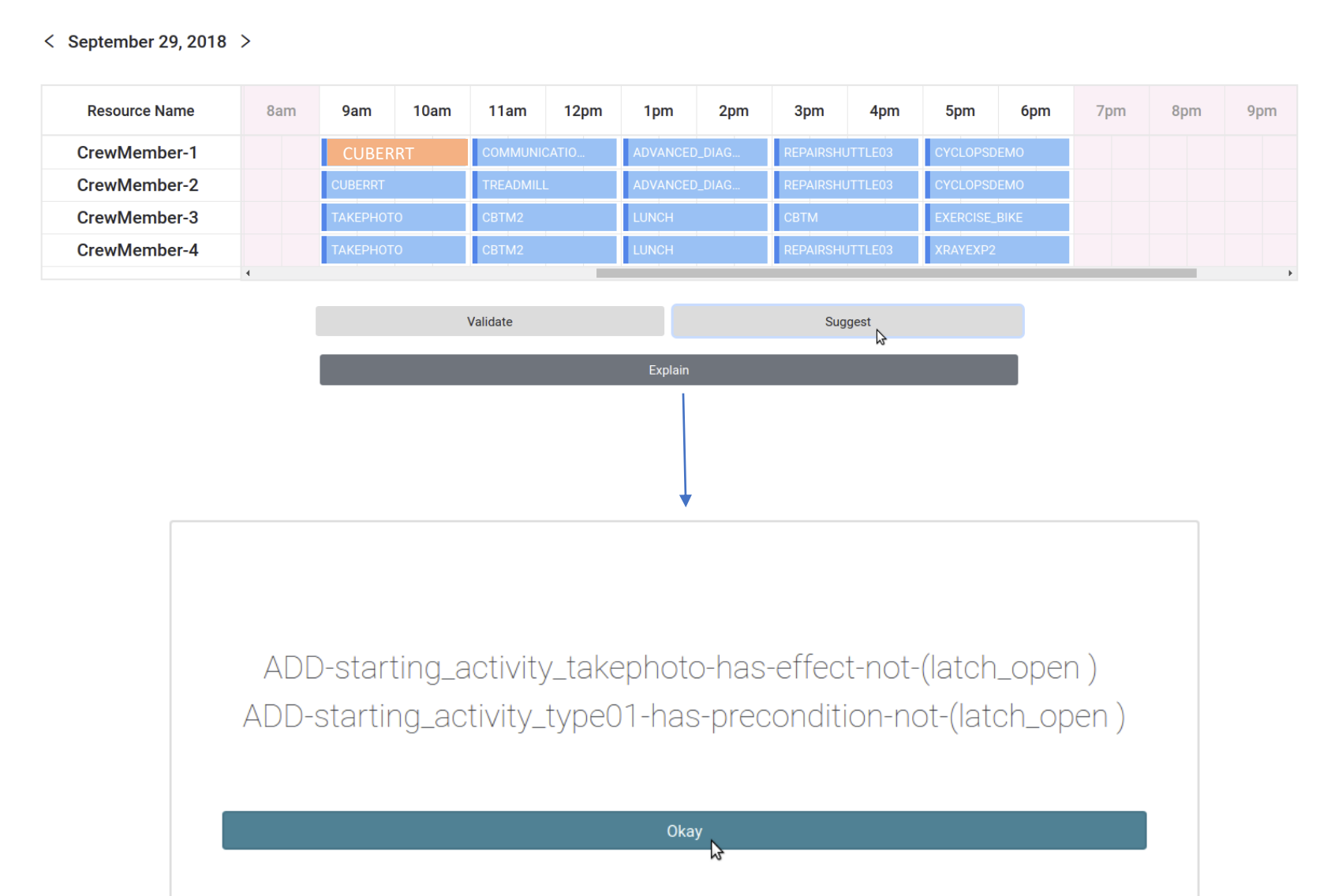
Plan Correction and Plan Suggestion

- Possible plan completions given a partial plan can be suggested using Probabilistic Plan Recognition technology.



Explaining Suggested Plans

- When generated plans look inexplicable to humans, we can provide explanations based on model differences between the human and the system.



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